

# NAG Fortran Library Routine Document

## C06LAF

**Note:** before using this routine, please read the Users' Note for your implementation to check the interpretation of ***bold italicised*** terms and other implementation-dependent details.

### 1 Purpose

C06LAF estimates values of the inverse Laplace transform of a given function using a Fourier series approximation. Real and imaginary parts of the function, and a bound on the exponential order of the inverse, are required.

### 2 Specification

```

SUBROUTINE C06LAF(FUN, N, T, VALINV, ERREST, RELERR, ALPHAB, TFAC,
1              MXTERM, NTERMS, NA, ALOW, AHIGH, NFEVAL, WORK, IFAIL)
  INTEGER      N, MXTERM, NTERMS, NA, NFEVAL, IFAIL
  real        T(N), VALINV(N), ERREST(N), RELERR, ALPHAB, TFAC,
1              ALOW, AHIGH, WORK(4*MXTERM+2)
  EXTERNAL    FUN

```

### 3 Description

Given a function  $F(p)$  defined for complex values of  $p$ , this routine estimates values of its inverse Laplace transform by Crump's method (Crump (1976)). (For a definition of the Laplace transform and its inverse, see the C06 Chapter Introduction.)

Crump's method applies the epsilon algorithm (Wynn (1956)) to the summation in Durbin's Fourier series approximation (Durbin (1974))

$$f(t_j) \simeq \frac{e^{at_j}}{\tau} \left[ \frac{1}{2}F(a) - \sum_{k=1}^{\infty} \left\{ \operatorname{Re}\left(F\left(a + \frac{k\pi i}{\tau}\right)\right) \cos \frac{k\pi t_j}{\tau} - \operatorname{Im}\left(F\left(a + \frac{k\pi i}{\tau}\right)\right) \sin \frac{k\pi t_j}{\tau} \right\} \right],$$

for  $j = 1, 2, \dots, n$ , by choosing  $a$  such that a prescribed relative error should be achieved. The method is modified slightly if  $t = 0.0$  so that an estimate of  $f(0.0)$  can be obtained when it has a finite value.  $\tau$  is calculated as  $t_{fac} \times \max(0.01, t_j)$ , where  $t_{fac} > 0.5$ . The user specifies  $t_{fac}$  and  $\alpha_b$ , an upper bound on the exponential order  $\alpha$  of the inverse function  $f(t)$ .  $\alpha$  has two alternative interpretations:

- (i)  $\alpha$  is the smallest number such that

$$|f(t)| \leq m \times \exp(\alpha t)$$

for large  $t$ ,

- (ii)  $\alpha$  is the real part of the singularity of  $F(p)$  with largest real part.

The method depends critically on the value of  $\alpha$ . See Section 8 for further details. The routine calculates at least two different values of the parameter  $a$ , such that  $a > \alpha_b$ , in an attempt to achieve the requested relative error and provide error estimates. The values of  $t_j$ , for  $j = 1, 2, \dots, n$ , must be supplied in monotonically increasing order. The routine calculates the values of the inverse function  $f(t_j)$  in decreasing order of  $j$ .

### 4 References

Durbin F (1974) Numerical inversion of Laplace transforms: An efficient improvement to Dubner and Abate's method *Comput. J.* **17** 371–376

Crump K S (1976) Numerical inversion of Laplace transforms using a Fourier series approximation *J. Assoc. Comput. Mach.* **23** 89–96

Wynn P (1956) On a device for computing the  $e_m(S_n)$  transformation *Math. Tables Aids Comput.* **10** 91–96

## 5 Parameters

1: FUN – SUBROUTINE, supplied by the user. *External Procedure*

FUN must evaluate the real and imaginary parts of the function  $F(p)$  for a given value of  $p$ .

Its specification is:

<pre style="margin: 0;">SUBROUTINE FUN(PR, PI, FR, FI)   <b>real</b>          PR, PI, FR, FI</pre>
<pre style="margin: 0;">1:  PR – <b>real</b>                                <i>Input</i> 2:  PI – <b>real</b>                                <i>Input</i></pre>
<p style="margin: 0;"><i>On entry:</i> the real and imaginary parts of the argument <math>p</math>.</p>
<pre style="margin: 0;">3:  FR – <b>real</b>                                <i>Output</i> 4:  FI – <b>real</b>                                <i>Output</i></pre>
<p style="margin: 0;"><i>On exit:</i> the real and imaginary parts of the value <math>F(p)</math>.</p>

FUN must be declared as EXTERNAL in the (sub)program from which C06LAF is called. Parameters denoted as *Input* must **not** be changed by this procedure.

2: N – INTEGER *Input*

*On entry:* the number of points,  $n$ , at which the value of the inverse Laplace transform is required.

*Constraint:*  $N \geq 1$ .

3: T(N) – **real** array *Input*

*On entry:* each  $T(j)$  must specify a point at which the inverse Laplace transform is required, for  $j = 1, 2, \dots, n$ .

*Constraint:*  $0.0 \leq T(1) < T(2) < \dots < T(n)$ .

4: VALINV(N) – **real** array *Output*

*On exit:* an estimate of the value of the inverse Laplace transform at  $t = T(j)$ , for  $j = 1, 2, \dots, n$ .

5: ERREST(N) – **real** array *Output*

*On exit:* an estimate of the error in  $VALINV(j)$ . This is usually an estimate of relative error but, if  $VALINV(j) < RELERR$ ,  $ERREST(j)$  estimates the absolute error.  $ERREST(j)$  is unreliable when  $VALINV(j)$  is small but slightly greater than  $RELERR$ .

6: RELERR – **real** *Input*

*On entry:* the required relative error in the values of the inverse Laplace transform. If the absolute value of the inverse is less than  $RELERR$ , then absolute accuracy is used instead.  $RELERR$  must be in the range  $0.0 \leq RELERR < 1.0$ . If  $RELERR$  is set too small or to 0.0, then the routine uses a value sufficiently larger than *machine precision*.

7: ALPHAB – **real** *Input*

*On entry:*  $\alpha_b$ , an upper bound for  $\alpha$  (see Section 3). Usually,  $\alpha_b$  should be specified equal to, or slightly larger than, the value of  $\alpha$ . If  $\alpha_b < \alpha$  then the prescribed accuracy may not be achieved or completely incorrect results may be obtained. If  $\alpha_b$  is too large the routine will be inefficient and convergence may not be achieved.

**Note:** it is as important to specify  $\alpha_b$  correctly as it is to specify the correct function for inversion.

- 8: TFAC – *real* *Input*  
*On entry:*  $t_{fac}$ , a factor to be used in calculating the parameter  $\tau$ . Larger values (e.g., 5.0) may be specified for difficult problems, but these may require very large values of MXTERM.  
*Suggested value:* TFAC = 0.8.  
*Constraint:* TFAC > 0.5.
- 9: MXTERM – INTEGER *Input*  
*On entry:* the maximum number of (complex) terms to be used in the evaluation of the Fourier series.  
*Suggested value:* MXTERM  $\geq$  100, except for very simple problems.  
*Constraint:* MXTERM  $\geq$  1.
- 10: NTERMS – INTEGER *Output*  
*On exit:* the number of (complex) terms actually used.
- 11: NA – INTEGER *Output*  
*On exit:* the number of values of  $a$  used by the routine. See Section 8.
- 12: ALOW – *real* *Output*  
*On exit:* the smallest value of  $a$  used in the algorithm. This may be used for checking the value of ALPHAB— see Section 8.
- 13: AHIGH – *real* *Output*  
*On exit:* the largest value of  $a$  used in the algorithm. This may be used for checking the value of ALPHAB— see Section 8.
- 14: NFEVAL – INTEGER *Output*  
*On exit:* the number of calls to FUN made by the routine.
- 15: WORK(4\*MXTERM+2) – *real* array *Workspace*
- 16: IFAIL – INTEGER *Input/Output*  
*On entry:* IFAIL must be set to 0, -1 or 1. Users who are unfamiliar with this parameter should refer to Chapter P01 for details.  
*On exit:* IFAIL = 0 unless the routine detects an error (see Section 6).

For environments where it might be inappropriate to halt program execution when an error is detected, the value -1 or 1 is recommended. If the output of error messages is undesirable, then the value 1 is recommended. Otherwise, because for this routine the values of the output parameters may be useful even if IFAIL  $\neq$  0 on exit, the recommended value is -1. **When the value -1 or 1 is used it is essential to test the value of IFAIL on exit.**

## 6 Error Indicators and Warnings

If on entry  $IFAIL = 0$  or  $-1$ , explanatory error messages are output on the current error message unit (as defined by X04AAF).

Errors or warnings detected by the routine:

$IFAIL = 1$

On entry,  $N < 1$ ,  
 or  $MXTERM < 1$ ,  
 or  $RELERR < 0.0$ ,  
 or  $RELERR \geq 1.0$ ,  
 or  $TFAC \leq 0.5$ .

$IFAIL = 2$

On entry,  $T(1) < 0.0$ ,  
 or  $T(1), T(2), \dots, T(N)$  are not in strictly increasing order.

$IFAIL = 3$

$T(N)$  is too large for this value of  $ALPHAB$ . If necessary, scale the problem as described in Section 8.

$IFAIL = 4$

The required accuracy cannot be obtained. It is possible that  $ALPHAB$  is less than  $\alpha$ . Alternatively, the problem may be especially difficult. Try increasing  $TFAC$ ,  $ALPHAB$  or both.

$IFAIL = 5$

Convergence failure in the epsilon algorithm. Some values of  $VALINV(j)$  may be calculated to the desired accuracy; this may be determined by examining the values of  $ERREST(j)$ . Try reducing the range of  $T$  or increasing  $MXTERM$ . If  $IFAIL = 5$  still results, try reducing  $TFAC$ .

$IFAIL = 6$

All values of  $VALINV(j)$  have been calculated but not all are to the requested accuracy; the values of  $ERREST(j)$  should be examined carefully. Try reducing the range of  $t$ , or increasing  $TFAC$ ,  $ALPHAB$  or both.

## 7 Accuracy

The error estimates are often very close to the true error but, because the error control depends on an asymptotic formula, the required error may not always be met. There are two principal causes of this: Gibbs' phenomena, and zero or small values of the inverse Laplace transform.

Gibbs' phenomena (see the C06 Chapter Introduction) are exhibited near  $t = 0.0$  (due to the method) and around discontinuities in the inverse Laplace transform  $f(t)$ . If there is a discontinuity at  $t = c$  then the method converges such that  $f(c) \rightarrow (f(c-) + f(c+))/2$ .

Apparent loss of accuracy, when  $f(t)$  is small, may not be serious. Crump's method keeps control of relative error so that good approximations to small function values may appear to be very inaccurate. If  $|f(t)|$  is estimated to be less than  $RELERR$  then this routine switches to absolute error estimation. However, when  $|f(t)|$  is slightly larger than  $RELERR$  the relative error estimates are likely to cause  $IFAIL = 6$ . If this is found inconvenient it can sometimes be avoided by adding  $k/p$  to the function  $F(p)$ , which shifts the inverse to  $k + f(t)$ .

Loss of accuracy may also occur for highly oscillatory functions.

More serious loss of accuracy can occur if  $\alpha$  is unknown and is incorrectly estimated. See Section 8.

## 8 Further Comments

### 8.1 Timing

The value of  $n$  is less important in general than the value of NTERMS. Unless the subroutine FUN is very inexpensive to compute, the timing is proportional to  $NA \times NTERMS$ . For simple problems  $NA = 2$  but in difficult problems  $NA$  may be somewhat larger.

### 8.2 Precautions

The user is referred to the C06 Chapter Introduction for advice on simplifying problems with particular difficulties, e.g., where the inverse is known to be a step function.

The method does not work well for large values of  $t$  when  $\alpha$  is positive. It is advisable, especially if  $IFAIL = 3$  is obtained, to scale the problem if  $|\alpha|$  is much greater than 1.0. See the C06 Chapter Introduction.

The range of values of  $t$  specified for a particular call should not be greater than about 10 units. This is because the method uses parameters based on the value  $T(n)$  and these tend to be less appropriate as  $t$  becomes smaller. However, as the timing of the routine is not especially dependent on  $n$ , it is usually far more efficient to evaluate the inverse for ranges of  $t$  than to make separate calls to the routine for each value of  $t$ .

The most important parameter to specify correctly is ALPHAB, an upper bound for  $\alpha$ . If, on entry, ALPHAB is sufficiently smaller than  $\alpha$  then completely incorrect results will be obtained with  $IFAIL = 0$ . Unless  $\alpha$  is known theoretically it is strongly advised that the user should test any estimated value used. This may be done by specifying a single value of  $t$  (i.e.  $T(n)$ ,  $n = 1$ ) with two sets of suitable values of TFAC, RELERR and MXTERM, and examining the resulting values of ALOW and AHIGH. The value of  $T(1)$  should be chosen very carefully and the following points should be borne in mind:

- (i)  $T(1)$  should be small but not too close to 0.0 because of Gibbs' phenomenon (see Section 7),
- (ii) the larger the value of  $T(1)$ , the smaller the range of values of  $a$  that will be used in the algorithm,
- (iii)  $T(1)$  should ideally not be chosen such that  $f(T(1)) = 0.0$  or a very small value. For suitable problems  $T(1)$  might be chosen as, say, 0.1 or 1.0 depending on these factors. The routine calculates ALOW from the formula

$$ALOW = ALPHAB - \frac{\ln(0.1 \times RELERR)}{2} \times \tau.$$

Additional values of  $a$  are computed by adding  $1/\tau$  to the previous value. As  $\tau = TFAC \times T(n)$ , it will be seen that large values of TFAC and RELERR will test for  $a$  close to ALPHAB. Small values of TFAC and RELERR will test for  $a$  large. If the result of both tests is  $IFAIL = 0$ , with comparable values for the inverse, then this gives some credibility to the chosen value of ALPHAB. The user should note that this test could be more computationally expensive than the calculation of the inverse itself. The example program (see Section 9) illustrates how such a test may be performed.

## 9 Example

The example program estimates the inverse Laplace transform of the function  $F(p) = 1/(p + 1/2)$ . The true inverse of  $F(p)$  is  $\exp(-t/2)$ . Two preliminary calls to the routine are made to verify that the chosen value of ALPHAB is suitable. For these tests the single value  $T(1) = 1.0$  is used. To test values of  $a$  close to ALPHAB, the values  $TFAC = 5.0$  and  $RELERR = 0.01$  are chosen. To test larger  $a$ , the values  $TFAC = 0.8$  and  $RELERR = 1.0E-3$  are used. Because the values of the computed inverse are similar and  $IFAIL = 0$  in each case, these tests show that there is unlikely to be a singularity of  $F(p)$  in the region  $-0.04 \leq \text{Re } p \leq 6.51$ .

## 9.1 Program Text

**Note:** the listing of the example program presented below uses *bold italicised* terms to denote precision-dependent details. Please read the Users' Note for your implementation to check the interpretation of these terms. As explained in the Essential Introduction to this manual, the results produced may not be identical for all implementations.

```

*      C06LAF Example Program Text
*      Mark 14 Revised.  NAG Copyright 1989.
*      .. Parameters ..
INTEGER          NMAX, MXTERM
PARAMETER       (NMAX=20,MXTERM=200)
INTEGER          NOUT
PARAMETER       (NOUT=6)
*      .. Local Scalars ..
real           AHIGH, ALOW, ALPHAB, RELERR, TFAC
INTEGER          I, IFAIL, N, NA, NFEVAL, NTERMS
*      .. Local Arrays ..
real           ERREST(NMAX), T(NMAX), TRUREL(NMAX),
+              TRURES(NMAX), VALINV(NMAX), WORK(4*MXTERM+2)
*      .. External Subroutines ..
EXTERNAL        CO6LAF, FUN
*      .. Intrinsic Functions ..
INTRINSIC       ABS, EXP, real
*      .. Executable Statements ..
WRITE (NOUT,*) 'C06LAF Example Program Results'
WRITE (NOUT,*)
WRITE (NOUT,*) '(results may be machine-dependent)'
ALPHAB = -0.5e0
T(1) = 1.0e0
*
*      Test for values of a close to ALPHAB.
*
RELERR = 0.01e0
TFAC = 7.5e0
WRITE (NOUT,*)
WRITE (NOUT,99997) 'Test with T(1) =', T(1)
WRITE (NOUT,*)
WRITE (NOUT,99999) '  MXTERM =', MXTERM, '  TFAC =', TFAC,
+ '  ALPHAB =', ALPHAB, '  RELERR =', RELERR
IFAIL = -1
*
CALL CO6LAF(FUN,1,T,VALINV,ERREST,RELERR,ALPHAB,TFAC,MXTERM,
+          NTERMS,NA,ALOW,AHIGH,NFEVAL,WORK,IFAIL)
*
IF (IFAIL.GT.0 .AND. IFAIL.LT.5) GO TO 60
WRITE (NOUT,*)
WRITE (NOUT,*) '  T          Result          exp(-T/2)  ',
+ 'Relative error  Error estimate'
TRURES(1) = EXP(-T(1)/2.0e0)
TRUREL(1) = ABS((VALINV(1)-TRURES(1))/TRURES(1))
WRITE (NOUT,99998) T(1), VALINV(1), TRURES(1), TRUREL(1),
+ ERREST(1)
WRITE (NOUT,*)
WRITE (NOUT,99996) '  NTERMS =', NTERMS, '  NFEVAL =', NFEVAL,
+ '  ALOW =', ALOW, '  AHIGH =', AHIGH, '  IFAIL =', IFAIL
*
*      Test for larger values of a.
*
RELERR = 1.0e-3
TFAC = 0.8e0
WRITE (NOUT,*)
WRITE (NOUT,99997) 'Test with T(1) =', T(1)
WRITE (NOUT,*)
WRITE (NOUT,99999) '  MXTERM =', MXTERM, '  TFAC =', TFAC,
+ '  ALPHAB =', ALPHAB, '  RELERR =', RELERR
IFAIL = -1
*
CALL CO6LAF(FUN,1,T,VALINV,ERREST,RELERR,ALPHAB,TFAC,MXTERM,
+          NTERMS,NA,ALOW,AHIGH,NFEVAL,WORK,IFAIL)
*
IF (IFAIL.GT.0 .AND. IFAIL.LT.5) GO TO 60

```

```

WRITE (NOUT,*)
WRITE (NOUT,*) ' T      Result      exp(-T/2) ',
+ 'Relative error Error estimate'
TRURES(1) = EXP(-T(1)/2.0e0)
TRUREL(1) = ABS((VALINV(1)-TRURES(1))/TRURES(1))
WRITE (NOUT,99998) T(1), VALINV(1), TRURES(1), TRUREL(1),
+ ERREST(1)
WRITE (NOUT,*)
WRITE (NOUT,99996) ' NTERMS =', NTERMS, ' NFEVAL =', NFEVAL,
+ ' ALLOW =', ALLOW, ' AHIGH =', AHIGH, ' IFAIL =', IFAIL
*
WRITE (NOUT,*)
WRITE (NOUT,*) 'Compute inverse'
WRITE (NOUT,*)
WRITE (NOUT,99999) ' MXTERM =', MXTERM, ' TFAC =', TFAC,
+ ' ALPHAB =', ALPHAB, ' RELERR =', RELERR
WRITE (NOUT,*)
WRITE (NOUT,*) ' T      Result      exp(-T/2) ',
+ 'Relative error Error estimate'
N = 5
DO 20 I = 1, N
    T(I) = real(I)
20 CONTINUE
IFAIL = -1
*
CALL C06LAF(FUN,N,T,VALINV,ERREST,RELERR,ALPHAB,TFAC,MXTERM,
+ NTERMS,NA,ALLOW,AHIGH,NFEVAL,WORK,IFAIL)
*
IF (IFAIL.GT.0 .AND. IFAIL.LT.5) GO TO 60
DO 40 I = 1, N
    TRURES(I) = EXP(-T(I)/2.0e0)
    TRUREL(I) = ABS((VALINV(I)-TRURES(I))/TRURES(I))
40 CONTINUE
WRITE (NOUT,99998) (T(I),VALINV(I),TRURES(I),TRUREL(I),ERREST(I),
+ I=1,N)
60 WRITE (NOUT,*)
WRITE (NOUT,99996) ' NTERMS =', NTERMS, ' NFEVAL =', NFEVAL,
+ ' ALLOW =', ALLOW, ' AHIGH =', AHIGH, ' IFAIL =', IFAIL
*
99999 FORMAT (1X,A,I4,A,F6.2,A,F6.2,A,1P,e8.1)
99998 FORMAT (1X,F4.1,7X,F6.3,9X,F6.3,8X,e8.1,8X,e8.1)
99997 FORMAT (1X,A,F4.1)
99996 FORMAT (1X,A,I4,A,I4,A,F7.2,A,F7.2,A,I2)
END
*
SUBROUTINE FUN(PR,PI,FR,FI)
Function to be inverted
* .. Scalar Arguments ..
real FI, FR, PI, PR
* .. External Subroutines ..
EXTERNAL AO2ACF
* .. Executable Statements ..
CALL AO2ACF(1.0e0,0.0e0,PR+0.5e0,PI,FR,FI)
*
RETURN
END

```

## 9.2 Program Data

None.

## 9.3 Program Results

C06LAF Example Program Results

(results may be machine-dependent)

Test with  $T(1) = 1.0$

MXTERM = 200 TFAC = 7.50 ALPHAB = -0.50 RELERR = 1.0E-02

T	Result	exp(-T/2)	Relative error	Error estimate
1.0	0.607	0.607	0.1E-02	0.4E-02

NTERMS = 18 NFEVAL = 36 ALOW = -0.04 AHIGH = 0.09 IFAIL = 0

Test with T(1) = 1.0

MXTERM = 200 TFAC = 0.80 ALPHAB = -0.50 RELERR = 1.0E-03

T	Result	exp(-T/2)	Relative error	Error estimate
1.0	0.607	0.607	0.2E-04	0.8E-04

NTERMS = 13 NFEVAL = 28 ALOW = 5.26 AHIGH = 6.51 IFAIL = 0

Compute inverse

MXTERM = 200 TFAC = 0.80 ALPHAB = -0.50 RELERR = 1.0E-03

T	Result	exp(-T/2)	Relative error	Error estimate
1.0	0.607	0.607	0.5E-04	0.3E-03
2.0	0.368	0.368	0.7E-05	0.9E-04
3.0	0.223	0.223	0.2E-04	0.8E-04
4.0	0.135	0.135	0.1E-04	0.8E-04
5.0	0.082	0.082	0.2E-04	0.8E-04

NTERMS = 23 NFEVAL = 43 ALOW = 0.65 AHIGH = 0.90 IFAIL = 0

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